

OTREC2019 Santa Cruz quality checked radiosonde data

Field campaign: Organization of Eastern Pacific Convection 2019 (OTREC2019)

Quality check:

Stipo Sentic, research associate

Climate and Water Consortium

New Mexico Tech

801 Leroy Place, Socorro, NM 87801

stipo.sentic@nmt.edu (contact me with any data questions)

ORCID: 0000-0002-5250-6789

Radiosonde operators (alphabetically ordered):

Adriana Denise Formby-Fernandez (Embry-Riddle Aeronautical University)

Alejandro Jaramillo Moreno (University of Mexico)

Ana Juracic (Ericsson Nikola Tesla)

Benjamin R. Lintner (Rutgers University)

Jane Wilson Baldwin (Princeton University)

Jose Martinez Claros (New Mexico Tech)

Justin Whitaker (Colorado State University)

Lidia Huaman ChuquiHuaccha (Texas A&M University)

Melanie Bieli (Caltech)

Melissa Piper (Iowa State University)

Miguel Bernardez (University of Wisconsin-Madison)

Miranda Bitting (University of Delaware)

Patrick Dunn Orenstein (Columbia University)

Vijit Maithel (University of Wisconsin-Madison)

Xin David Wei (Harvard University)

Zane Martin (Columbia University)

Zeyuan Hu (Harvard University)

1.0 Data Set Overview

For an overview of the scientific goals of OTREC2019 please refer to the EOL campaign web page (https://www.eol.ucar.edu/field_projects/otrec).

The Santa Cruz radiosondes were launched from the University of Costa Rica campus in collaboration with Marcial Garbanzo and Anna Maria Duran of the Costa Rica University. The team performed mandatory launches at 00 and 12 UTC, and often more than two launches per day. 131 launches were performed from 20 Aug to 30 Sep 2019, which includes intensive launch periods. Table 1 summarizes the number of launches per day for different time periods. Figure 1 summarizes the radiosonde flight paths from the launch location.

Table 1: Radiosonde launch frequency.

Date(s)	Number of launches per day
Aug 20-30, Sep 16, 25-26, 28	2
Sep 1-2, 9-15, 18-21, 24, 27,29	3
Sep 17	4
Sep 6, 22	5
Sep 3, 8	6
Sep 4-5, 7, 23	7

2.0 Instrument Description

Radiosonde sounding system Internet iMet-3050A Portable 403MHz Antenna/Receiver was used with the iMet-4 radiosonde (specifications are attached at the end of this summary file). iMetOS-II (version 3.127.1) radiosonde receiver software was used to receive and record the data in 1 second intervals.

3.0 Data Collection and Processing

The iMet software automatically does some corrections such as time-lag, according to Miloshevich et al. (2004), and it corrects for the temperature difference between the sensor and the air temperature as well, by using:

$$CorrectedRH = RawRH * \frac{\text{saturation vapor pressure}(RH \text{ sensor temperature})}{\text{saturation vapor pressure}(AT \text{ sensor temperature})}$$

Challenges of radiosonde relative humidity measurements in the upper troposphere and stratosphere are outlined in Nash (2015) and Miloshevich et al. (2001). Note that the iMet-4 radiosonde has a thin-film capacitor if you choose to explore the Nash (2015) report in chapter 5 on relative humidity measurements. We left relative humidity data unaltered above 11 km, but suggest to the user to apply some smoothing above 11 km.

In addition to above automatic quality control we did a subjective visual inspection of the radiosonde data, and deleted suspicious spikes and bad data. We provide this quality checked data in this dataset.

4.0 Data Format

We provide the data in a ASCII space delimited format. Table 2 lists all the provided quality checked variables. We use the following format for the written data: "%6.1f %10.2f %10.1f %10.6f %10.6f %10.2f %10.2f %10.2f %10.1f %5i %10.1f %10.1f %10.2f %10.1f\n". Missing or bad data was replaced with -9999.

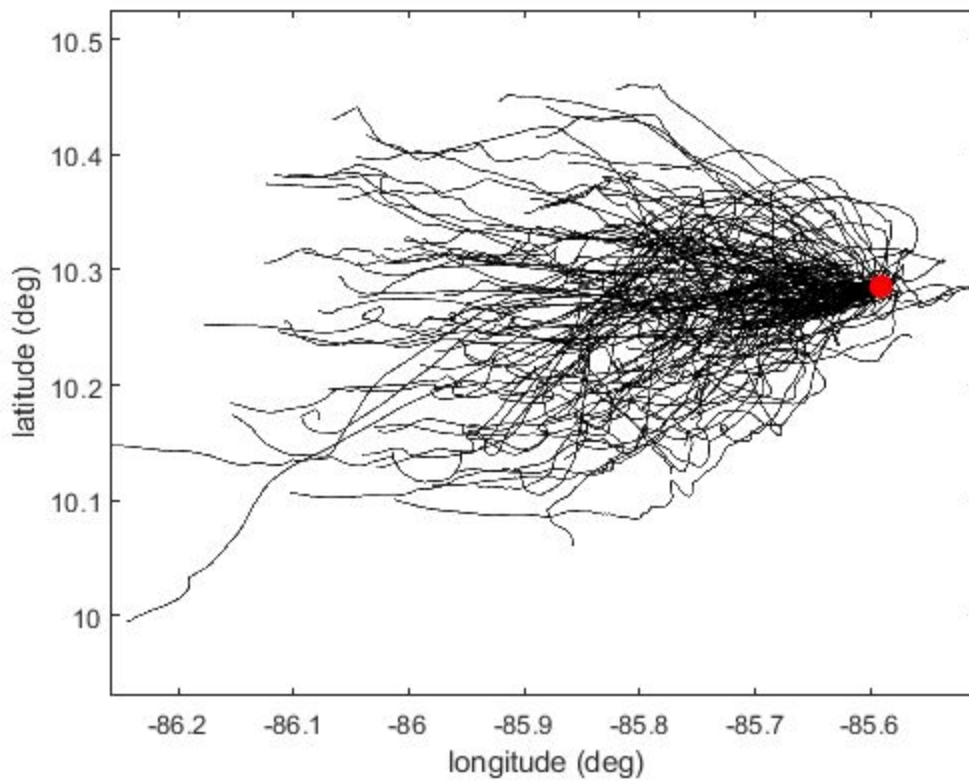


Figure 1: Radiosonde paths (a total of 131), relative to the launch site (Santa Cruz, red point). Maximum deviation from the launch site is -0.6669 degrees longitude, and about -0.2909 degrees latitude.

Table 2: Provided data and units. See attached radiosonde specification sheet for measurement accuracy and uncertainty.

Field	Unit	Note
time	seconds	Radiosonde flight time
pressure	hPa	Barometric pressure
MSL height	meters	Mean sea level height
longitude	degrees	Longitude east
latitude	degrees	Latitude north
temperature	degrees C	
virtual t.	Degrees C	Virtual temperature
RH	%	Relative humidity
wind speed	m/s	
wind dir.	degrees	Wind direction
u	m/s	Zonal wind component
v	m/s	Meridional wind component
ascent rate	m/s	Radiosonde ascent rate
GPMMSL	m	GPS mean see level height

5.0 Data Remarks

Using visual quality checking we found the following issues:

- 1) Sonde on 2019-08-27, 12:01, bad data 12.7-13.2 km, 14.81-14.83km, in temperatures, and relative humidity.
- 2) Sonde on 2019-09-05, 13:51, bad relative humidity 8.66-8.71km, bad temperatures 9.14-9.17 km, and 9.38-9.41 km.
- 3) Sonde on 2019-09-05, 23:51, bad relative humidity 6.65 - 6.72 km.
- 4) Sonde on 2019-09-06, 21:54, bad sonde, there was a lot of missing data in this sonde, which the radiosonde software interpolated. Also it is incomplete, goes up to 7 km only.

- 5) Sonde on 2019-09-08, 21:53, bad temperatures and relative humidity data 1-7 km.
- 6) Sonde on 2019-09-15, 23:40 incomplete. Goes up to about 5 km.
- 7) Sonde on 2019-09-18, 17:57, bad temperatures data from 4 to 7.7 km.
- 8) Sonde on 2019-09-19, 23:41, incomplete. Goes up to 6 km.
- 9) Sonde on 2019-09-20, 23:51, incomplete. Goes up to 1.4 km.
- 10) Sonde on 2019-09-21, 17:49, bad relative humidity data 7.8-8 km.
- 11) Sonde on 2019-09-22, 8:55, bad temperatures and relative humidity data 4.6-5.8 km.
- 12) Sonde on 2019-09-22, 11:54, bad temperatures and relative humidity data 2.5 - 7.1 km.
- 13) Sonde on 2019-09-26, 18:16, incomplete. Goes up to about 1.2 km.
- 14) Sonde on 2019-09-27, 17:52, bad temperatures and relative humidity data from 6 to 7.7 km.

All the bad data above was replaced with a '-9999' value. We see that sondes under items 4, 5, 7, 11, 12, and 14 have large chunks of missing data, and that sondes under items 4, 6, 8, 9, and 13 are incomplete, i.e. do not cover the whole troposphere.

6.0 References

Miloshevich, L.M., A. Paukkunen, H. Vömel, and S.J. Oltmans, 2004: Development and Validation of a Time-Lag Correction for Vaisala Radiosonde Humidity Measurements. *J. Atmos. Oceanic Technol.*, 21, 1305–1327.

Miloshevich, L.M., H. Vömel, A. Paukkunen, A.J. Heymsfield, and S.J. Oltmans, 2001: Characterization and Correction of Relative Humidity Measurements from Vaisala RS80-A Radiosondes at Cold Temperatures. *J. Atmos. Oceanic Technol.*, 18, 135–156.

Nash, J., 2015, Measurement of upper-air pressure, temperature, and humidity. World Meteorological Organization, Instrument and Observing Methods, report #121, United Kingdom.



iMet-4 Radiosonde

403 MHz GPS Synoptic

Technical Data Sheet

Temperature and Humidity

The iMet-4 measures air temperature with a small glass bead thermistor. Its small size minimizes effects caused by long and short-wave radiation and ensures fast response times.

The humidity sensor is a thin-film capacitive polymer that responds directly to relative humidity. The sensor incorporates a temperature sensor to minimize errors caused by solar heating.

Pressure and Height

As recommended by GRUAN³, the iMet-4 is equipped with a pressure sensor to calculate height at lower levels in the atmosphere. Once the radiosonde reaches the optimal height, pressure is derived using GPS altitude combined with temperature and humidity data.

The pressure sensor facilitates the use of the sonde in field campaigns where a calibrated barometer is not available to establish an accurate ground observation for GPS-derived pressure. For synoptic use, the sensor is bias adjusted at ground level.

Winds

Data from the radiosonde's GPS receiver is used to calculate wind speed and direction.

Radiosonde Data Transmission

The iMet-4 radiosonde can transmit to an effective range of over 250 km*.

A 6 kHz peak-to-peak FM transmission maximizes efficiency and makes more channels available for operational use. Seven frequency selections are pre-programmed - with custom programming available.

Calibration

The iMet-4's temperature and humidity sensors are calibrated using NIST traceable references to yield the highest data quality.

Benefits

- Superior PTU performance
- Lightweight, compact design
- No assembly or recalibration required
- GRUAN³ qualified (pending)
- Status LED indicates transmit frequency selection and 3-D GPS solution
- Simple one-button user interface

* Subject to ground station, balloon size and atmospheric conditions

¹ All uncertainties expressed at a 95% confidence level

² Primary atmospheric pressure derived by GPS altitude

³ GECOS Reference Upper-Air Network

Specifications subject to change without notice, Rev 11 190801

MEASUREMENTS				
Measurement cycle	1 Hz	GEOPOTENTIAL HEIGHT		Pressure derived
		Measurement range		SFC to 40 km
		Resolution		0.1 m
TEMPERATURE SENSORS	Glass Bead	Combined Uncertainty/Reproducibility ¹		
Manufacturer	Shibaura	1080 - 400 hPa		15 m / 10 m
Measurement range	+60°C to -90°C	400 - 10 hPa		200 m / 150 m
Resolution	0.01°C			
Response time: still air/ 5 ms ⁻¹ (1000 hPa)	2 / < 1 sec			
Repeatability in Calibration	0.2 C	GEOPOTENTIAL HEIGHT		GPS derived
Combined Uncertainty/Reproducibility ¹		Measurement range		SFC to 40 km
> 100 hPa	0.5 C / 0.3 C	Resolution		0.1 m
< 100 hPa	1.0 C / 0.75 C	Combined Uncertainty/Reproducibility ¹		
Night flight	0.3 C / 0.3 C	1080 - 400 hPa		30 m / 15 m
Solar correction	≤ 1.2 C	400 - 3 hPa		60 m / 20 m
HUMIDITY SENSOR	Capacitive Polymer	WIND SPEED AND DIRECTION		
Manufacturer	IST	Resolution		0.1 m/s / 1 degree
Measurement range	0-100 % RH	Speed		
Resolution	0.1%	Combined Uncertainty/Reproducibility ¹		0.5 / 0.25 m/s
Response time		Direction		
@ 25C	0.6 seconds	Combined Uncertainty/Reproducibility ¹		1 degree
@ 5C	5.2 seconds			
@ -10C	11 seconds			
@ -40C	61 seconds			
Repeatability in Calibration	5 %	TELEMETRY		
Uncertainty/Reproducibility ¹		Transmission type		Synthesized
> 0 C	5% / 3%	Maximum Range		> 250 km
-40 to 0 C	5% / 5%	Frequency stability		± 3 kHz
		Deviation, peak to peak		6 kHz
PRESSURE ²	Sensor	Output Power		~ 30 – 200 mW
Manufacturer	Measurement Specialties	Modulation		AFSK
Measurement range	1200 hPa - 10 hPa	Data Rate		1200 Baud
Resolution	0.01 hPa	Standard Frequencies	402, 402.5, 403, 403.5 404, 404.5, 405	
Response time	0.5 milliseconds	Custom Frequencies		Available
Uncertainty/Reproducibility ¹				
Whole range	2.0 / 1.5 hPa	GPS RECEIVER		
1200 - 400 hPa	1.0 / 0.75 hPa	Manufacturer / Type		U-Blox CAM-M8
400 hPa - 10 hPa	2.0 / 1.5 hPa	Cold Start Time		< 60 seconds (typical)
PRESSURE	GPS derived	OPERATIONAL DATA		
Measurement range	SFC to 3 hPa	Battery		Lithium
Resolution	0.1 hPa	Operating time		> 135 minutes
Uncertainty/Reproducibility ¹		Weight		120 grams
1080 - 400 hPa	2.0 / 1.5 hPa	Dimensions		Body (LWH): 139x67x31
400 hPa - 3 hPa	0.5 / 0.25 hPa			With boom (LWH): 235x67x31
		Calibration Stability		2 years

* Subject to ground station, balloon size and atmospheric conditions

¹ All uncertainties expressed at a 95% confidence level

² Primary atmospheric pressure derived by GPS altitude

³ GECOS Reference Upper-Air Network

Specifications subject to change without notice, Rev 11 190801



InterMet
International Met Systems
Grand Rapids, MI USA
www.intermetsystems.com