1. SAVANT/UIUCAerosolLidar/Final data

2. Dataset Author(s)

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3. Time of Interest

1	09/23/2018 23:02:49 - 09/24/2018 00:33:47
2	09/29/2018 22:06:50 - 09/30/2018 01:24:46
3	$10/12/2018\ 01:29:27 - 10/12/2018\ 06:57:19$
4	$10/15/2018\ 23:49:12 - 10/16/2018\ 06:28:06$
5	$10/18/2018\ 00:48:38 - 10/18/2018\ 07:58:5$
6	$10/23/2018\ 23:21:42 - 10/24/2018\ 07:16:37$
7	10/27/2018 18:18:36 - 10/27/2018 23:23:19
8	10/29/2018 18:53:32 - 10/30/2018 00:46:14
9	11/02/2018 16:58:03 - 11/03/2018 06:56:15
10	$11/07/2018\ 21:24:25 - 11/07/2018\ 23:38:54$
11	11/10/2018 17:20:01 - 11/10/2018 20:20:57
12	11/11/2018 19:01:09 - 11/11/2018 23:18:20
13	$11/14/2018\ 01:05:55 - 11/14/2018\ 07:41:01$

4. Area of Interest

The experiment location is on Crowley Rd, Mahomet Township, IL 61853. The lidar location from September 15th to October 14^{th} was 40° 12' 34" N 88° 24' 21" W (Figures 1 and 2).

The laser head was pointed in the NEE direction (pointing to 40° 12' 37.23" N 88° 24' 14.27" W, the intersection of the main and feeder gullies when the azimuth angle of the laser head was 0 degrees).

The woodboard supporting the lidar is 31 cm tall from the ground surface; lidar is 1.8 m tall from the woodboard.



Figure 1. Lidar setup from September 15th to October 14th, 2018

From October 15 2018:

The UIUC aerosol lidar was moved to $40^{\circ}12'35.97"$ N, $88^{\circ}24'16.03"$ W. The laser head was pointed in the NEE direction, pointing to $40^{\circ}12'37.23"$ N $88^{\circ}24'14.27"$ W (the intersection of the main and feeder gullies) when the azimuth angle of the laser head was 110 degrees; When the azimuth angle was 110 degrees and the zenith angle was -0.6 degrees, the laser touched the ground at $40^{\circ}12'37.23"$ N $88^{\circ}24'14.27"$ W.



Figure 2. Lidar locations before and from October 15th, 2018. Blue arrow: pointing to the intersection of the main and feeder gullies when the azimuth angle of the laser head was 110 degrees (intersection: 40° 12' 37.23" N 88° 24' 14.27" W) on or after October 15th.

The woodboard supporting the lidar was 7.4 degrees down from horizontal toward the main gully direction (blue arrow direction), and 0.2 degrees down in the west direction (Figures 2, 3 and 4).



Figure 3. Lidar setup from October 15, 2018 and onwards. Blue arrow: pointing to the intersection of the main and feeder gullies when the azimuth angle of the laser head was 110 degrees(intersection: 40° 12' 37.23" N 88° 24' 14.27" W).

a: view from northwest side of feeder gully



Blue arrow: pointing to the intersection of main and feeder gullies

Ground

b: view from intersection of main and feeder gullies to lidar direction



Ground

Figure 4, Woodboard setup.

5. Data Frequency

Log Interval (mm:ss): 00:04

6. Data Spatial Type

Each backscatter file represents 2-D raw scanning backscatter value. Binary Data Files Scalar data.

7. General Dataset Description

Lidar model: LR111-ESS-D200 Raman Depolarization LIDAR From Raymetrics company in Greece

The lidar measured a backscatter of aerosol in the air.

The dataset includes the binary data on the experiment date of 09/23/2018-09/24/2018, 09/29/2018-09/30/2018, 10/11/2018-10/12/2018, 10/15/2018-10/16/2018, 10/17/2018-10/18/2018, 10/23/2018-10/24/2018, 10/27/2018, 10/29/2018-10/30/2018, 11/02/2018-11/03/2018, 11/07/2018-11/08/2018, 11/10/2018, 11/11/2018-11/12/2018, and 11/13/2018-11/14/2018.

There are two types of scanning modes. The main scanning mode is RHI(Range-Height Indicator), and the other scanning mode is PPI(Plan Position Indicator).

Example data file name: R1892323.091335

File name explanation: R: Raymetrics (lidar company name), ##:year (18:2018 in this example file name), #: month (9: September; if it is a letter, A represents October and B November), ##:date (23 in this example),##:hour (23 in this example), ##: minute (09 in this example), ####:seconds (1335 is 13.35" in this example)

Scanning Data structure:

The data file format is a mixed ASCII-binary format where the first lines describe the measurement situation; below follows the dataset description and then the raw data itself as 32-bit integer values. Sample header information of RAW datafile (can be opened with any text editor) from LiDAR is shown below:

#Las	ser shots				n		Lat & L	on	Zenith &	Ground temp 8	
	R18A1801.003855 U-C_VOL_ 18/10// 22.0 162.0 30.0 0000013 0020 000 1 0 1 163 1 0 1 163 #Lass 1 1 1 16380 1 00 1 0 1 16380 1 00 1 1 2 16380 1 00 1 1 1 1 10 1 1 1 1 10 1 1 1 1 10 1 1 1 1 10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	start 2018 01:0 00.0 -1 20013 000 er freq. 780 3.75 780 3.75 780 3.75 550 3.75 550 3.75 350 3.75	end 0:37 18/10 0.0 00.2 10 355.p 0 355.p 0 0355.p 0 00355.s 0 00355.s 0 00355.s 0 00355.s 0 00355.s 0 00355.s 0 00357.o 0 00387.o 0 1	d 0/2018 00.0 009 000 009 000 009 000 009 000 009 000 009 0000 0000 000 000 000 000 000 000 000 000 000 000 000 000 0	elig 01:00: datase 000 12 000 00 000 12 000 00 12 000 00 000 000000	237 0170 237 0170 200013 0 000013 0 0000000000	23.7534 38. 23.7534 38. 2.500 BT0 4.3651 BC0 2.500 BT0 4.3651 BC0 2.100 BT1 4.3651 BC1 4.3651 BC1 4.3651 BC2 4.3651 BC2 4.3651 BC2 4.3651 BC2 4.3651 BC2	.0631	attributes for datasets	Press 15.0 1013.0 or 10	
			wavel	ength							

The first line contains the measurement's name which is exactly the same as the file

name, as explained above.

The second line contains more information about the location, start and stop time

and the external conditions.

- Location String with 8 Letters
- Start Time dd/mm/yyyy hh:mm:ss
- Stop Time dd/mm/yyyy hh:mm:ss
- Height asl. four digits (meter)
- Longitude four digits (including sign). One digit for decimal grades.
- Latitude four digits (including sign). One digit for decimal grades.
- Zenith angle two digits in degrees of this scan
- Azimuth angle two digits in degrees of this scan
- Ground Temperature (Celsius)
- Ground Pressure (hPa)

The third line contains the information of scanning scheme for all the scanned files:

- Start scanning azimuth angle (22.0° in this example)
- End scanning azimuth angle (162.0°)
- Scanning azimuth angle interval (30.0°)
- Start scanning zenith angle (00.0°)
- End scanning azimuth angle (-10.0°)
- Scanning azimuth angle interval (00.2°)

The fourth line contains information about the laser.

• Laser 1 number of shots integer 7 digits (how many laser shots were averaged in one profile)

- Pulse repetition frequency for Laser 1 integer 4 digits (Usually 10 or 20)
- Laser 2 Number of shots integer 7 digits
- Pulse repetition frequency for Laser 2 integer 4 digits
- number of datasets in the file integer 2 digits

The next lines that are in ASCII format are the dataset description. The parameters are divided by a space.

- 1 digit integer: 1 if dataset is present, 0 otherwise
- 1 digit integer: 0 for Analogue / Photon counting, 1 for Photon counting
- 1 digit integer: 1 for Laser source 1, 2 for Laser source 2.
- 5 digits integer: Number of bins (example 16,300 x 3.75m each bin = 61,125m)
- 1 digit integer: N/A
- 4 digits integer: PMT High Voltage in volts
- 2 digit real with 2 decimal: Bin width in meters
- String with 5 digits: Laser wavelength in nm
- dot and letter: Polarization, o _ no polarization, s _ perpendicular, p _ parallel
- 0 0 00 000 backward compatibility
- 2 digits integer: number of ADC bits in case of an analogue dataset, otherwise 0
- 6 digits integer: number of shots
- 1 digit real with 3 decimal: input range in mVolt in case of analogue dataset,
- discriminator level in case of photon counting.
- String with 2 letters: Dataset descriptor BT=analogue dataset, BC=photon counting
- And one hexadecimal number: the Transient Recorder number.

The dataset description is followed by an extra CRLF. The datasets are 32bit integer values. Datasets are separated by CRLF. The last dataset is followed by a CRLF. These CRLF are used as markers and can be used as check points for file integrity.

The RAW data files can be converted to ASCII format. A sample data after converting RAW files to ASCII is shown below. Each column corresponds to each line of above mentioned description. For example, 0 (mv) column corresponds to the first line of description: 1 0 1 163.....BT0.



3D_1.ini file structure (ASCII): scanning scheme file

[MulitScanns] comment: multiple scans Multi = 0 comment: multiple scanning type #Scanns = 1 comment: number of scanning repetition

Temp.dat

This file contains scanning information for data processing software packages from Raymetrics company.

8. File Names List names of files transferred:

See details in file folders.

9. Data Restrictions

None

10. Digital Object Identifier (DOI)

The DOI for this dataset is https://doi.org/10.26023/K47H-XYE9-JJ0N .

11. GCMD Keywords

AEROSOL BACKSCATTER