Title: Windsond Quality Controlled Data for PERiLS 2022

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1.0 Dataset Overview:

The 2022 PERiLS Windsond dataset was collected from 1 March 2022 to 30 April 2022 within the domain outlined on the PERiLS EOL database main page. Two Windsond platforms conducted deployments of up to 16 sondes on a single receiver from 22 March 2022 to 13 April 2022. These platforms conducted coordinated launches before switching to mobile mesonet data collection as the target QLCS approached the platforms' longitude.

2.0 Instrument Description:

The Windsond system used in PERiLS 2022 was developed by Sparv Embedded, a Swedish company. Each Windsond is a 12 gram styrofoam cup equipped with a temperature sensor, RH sensor, and a GPS chip on the computer board from which wind speed and direction are derived. Data points are collected at a 1 Hz frequency dependent on receiver connection, occasionally dropping to a 0.2-0.33 Hz frequency. The hardware details can be found in the Sparv Windsond Catalog along with an overview in the table below.

Variable Specifications:

| Temperature | Sensor Type: Band Gap Measurement Range: -40 to 80 °C Accuracy: 0.3 °C Resolution: 0.01 °C Response Time: 6 sec | |
|------------------------|---|--|
| Relative Humidity (RH) | Sensor Type: Capacitive Measurement Range: 0 to 100% Accuracy: 2.0% Resolution: 0.05% Response TIme: 6 sec | |
| Pressure | Measurement Range: 300 to 1100 hPa Accuracy: 1.0 hPa Resolution: 0.02 hPa | |
| Wind Speed | Measurement Range: 0 to 150 m/s Accuracy: ca 5% Resolution: 0.1 m/s | |
| Wind Direction | Measurement Range: 0 to 360° Accuracy: Depends on GPS connectivity Resolution: 0.1° | |

Sparv Embedded has developed multi-sonde receivers to allow for multiple sondes to be launched from a single receiver and collect data from the receiver simultaneously. In this field campaign, 16 sonde RR2 receivers were used for the Windsond platform.

3.0 Data Collection and Processing:

Deployments dates outlined below including the number of sondes and launch location of each platform launching in the deployment:

| Date | Number of Sondes | Latitude | Longitude |
|---------------|------------------|------------------------|--------------------------|
| 22 March 2022 | 16 | 33.053152 33.105497 | -88.295732 -88.51376 |
| 30 March 2022 | 33 | 33.263133 33.354472 | -88.586992 -88.621435 |
| 05 April 2022 | 4 | 32.197051666 | -86.419445 |
| 13 April 2022 | 28 | 36.670777 35.94529 | -89.516753 -90.25718 |

The Windsond data was qc'd by flight for each deployment. The data collected between when a sonde was turned on and launched was excluded. This was done by determining the point at which the altitude was continually increasing for 100 m and when the ascent rate exceeded 2 m/s. The flight altitude was then corrected if the raw agl altitude was less than 0 m.

Dew point temperature was derived in post processing from the raw relative humidity and temperature at each data point. When the relative humidity value exceeds 100%, the relative humidity values were corrected such that values exceeding 100% were allowed, but a nan value was assigned to the dew point temperature field.

In addition, the wind speed and direction fields were smoothed by a cubic spline interpolation from the 1 Hz data. The number of knots selected for the cubic spline was determined independently for each flight in order to output the same amount of smoothing for each flight. The smoothness threshold value was found by calculating the difference in hodograph length between uncorrected and corrected wind profiles of a Vaisala radiosonde dataset collected during the Targeted Observations by Radars and UAS of Supercells (TORUS) campaign.

4.0 Data Format:

The data is comma-separated value formatted with headers for each variable in the first row. The filename is output in the following format:

{Platform name}_{Date of launch YYYYMMDD}_{time of launch (UTC) in HHMM}_{number in deployment if multiple sondes were launched each minute)}.csv

The heading descriptions are as follows:

Date when the datapoint was taken (with respect to the

UTC time)

hour UTC decimal hour of each datapoint

time UTC time in HH:MM:SS for each datapoint

lat_deg_N Latitude derived from onboard GPS (decimal degrees)
lon deg E Longitude derived from onboard GPS (decimal degrees)

elev_MSL_m Raw altitude (MSL) in meters elev_AGL_m Relative altitude (AGL) in meters

temp1 C Raw temperature values in degrees Celsius

tempD_C Derived dewpoint temperature values in degrees Celsius

RH Raw Relative Humidity in percent

hPa Pressure in hectopascals

Dir_deg Raw GPS derived wind direction in degrees

spd_mPerSRaw GPS derived wind speed in meters per secondcorr_dir_degSmoothed GPS derived wind direction in degreescorr_spd_mPerSSmoothed derived wind speed in meters per second

Nan values are denoted by 'nan' in the data columns. Data gaps occur when the Windsonds lose reception with the receiver for greater than five seconds.

5.0 Data Remarks:

Windsondes are a relatively new instrument (within ~10 years) and haven't been objectively compared with other instruments to understand biases in thermodynamic and kinematic variables. Therefore no corrections were made to account for any potential biases in the thermodynamic variables. This includes any correction of surface values using mobile mesonets or other surface observations. Results from a study in 2023 may lead to updates in thermodynamic corrections in the future.

One additional note: Several receivers issues occurred during the first deployment (22 March 2022) that led to errant data points as several Windsonds connected to multiple receivers during their individual flights. These data points are visible in the data and have not been corrected at this time. Please reach out to the lead author with any questions regarding this specific deployment.

6.0 References:

https://sparvembedded.com/products/windsond/